



# Hips do lie! A position-aware mobile fall detection system

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Heiner Stuckenschmidt, and Christian Becker



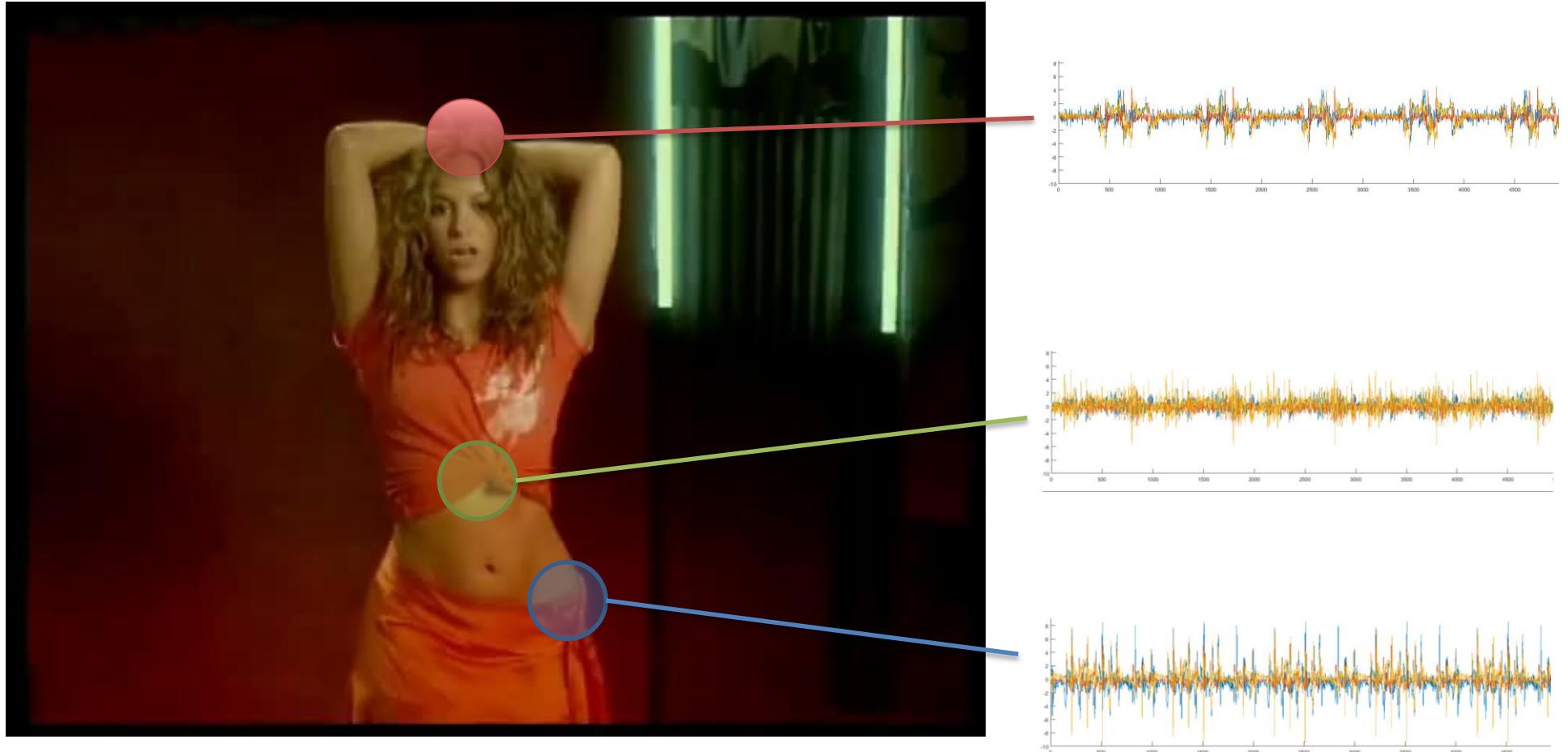
# Proposition

“

*So be wise and keep on  
Reading the signs of my body  
And I'm on tonight you know  
my **hips don't lie.***

SHAKIRA: “HIPS DON’T LIE” (2005)

# Alternative Proposition



Observation:

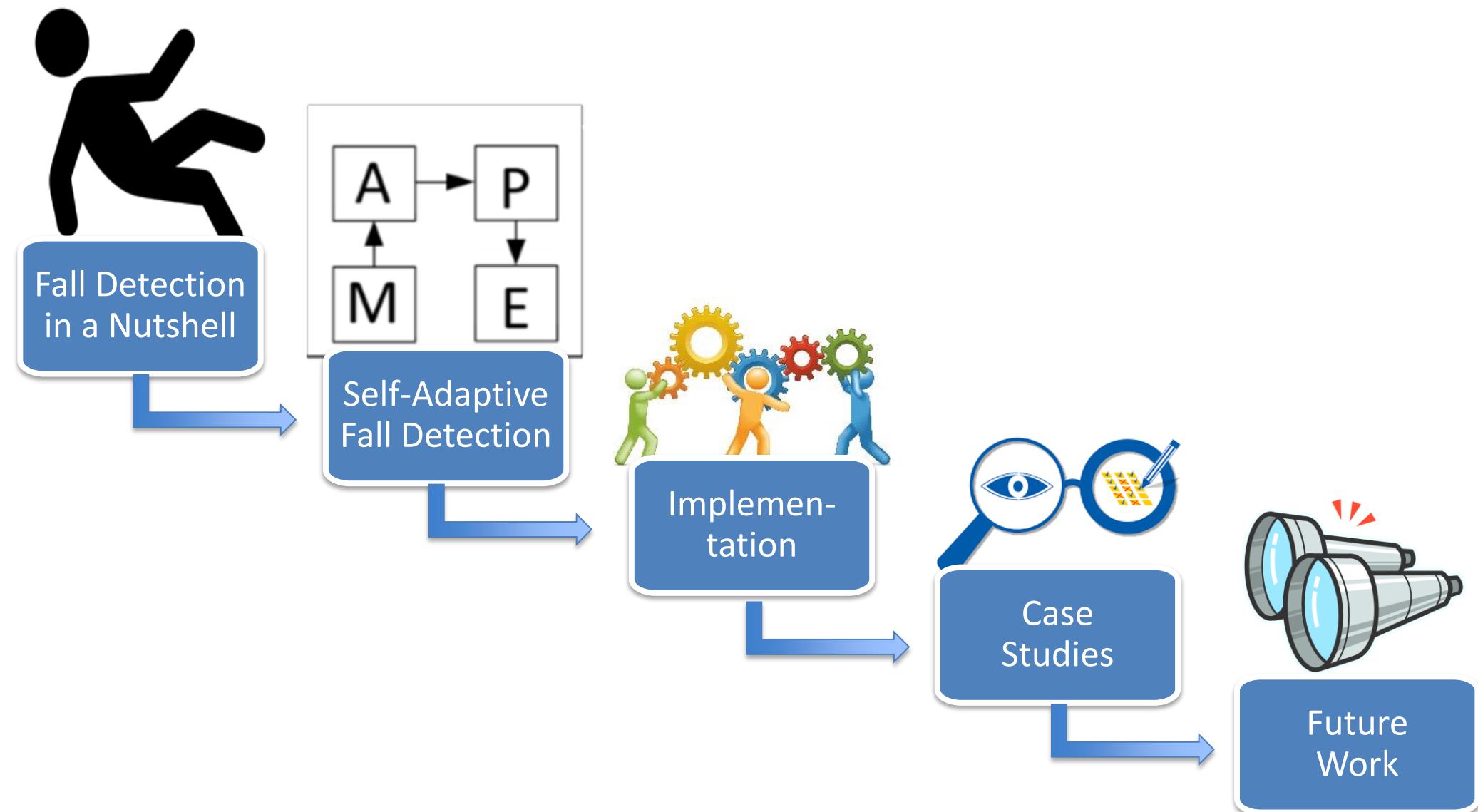
*Hips might not be the most reliable source of information*

# Research Question



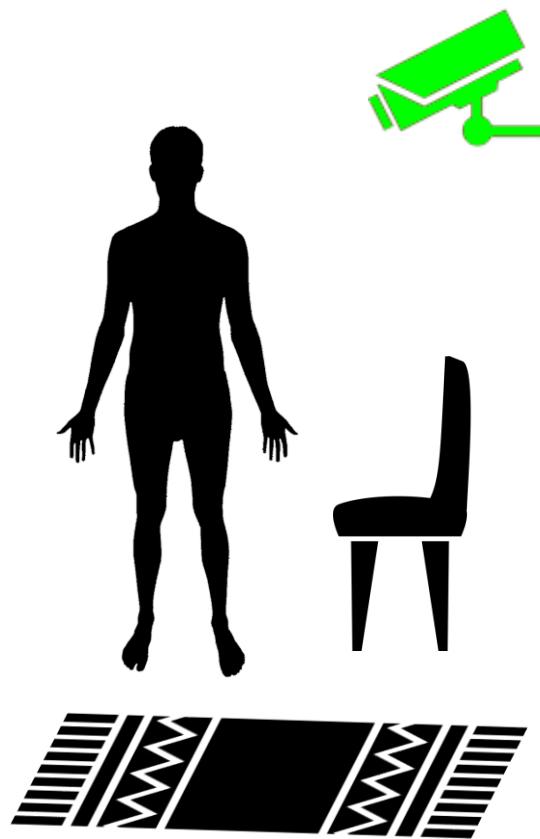
*How can a mobile fall detection system react to changes in the sensor position?*

# What to Expect from this Presentation?

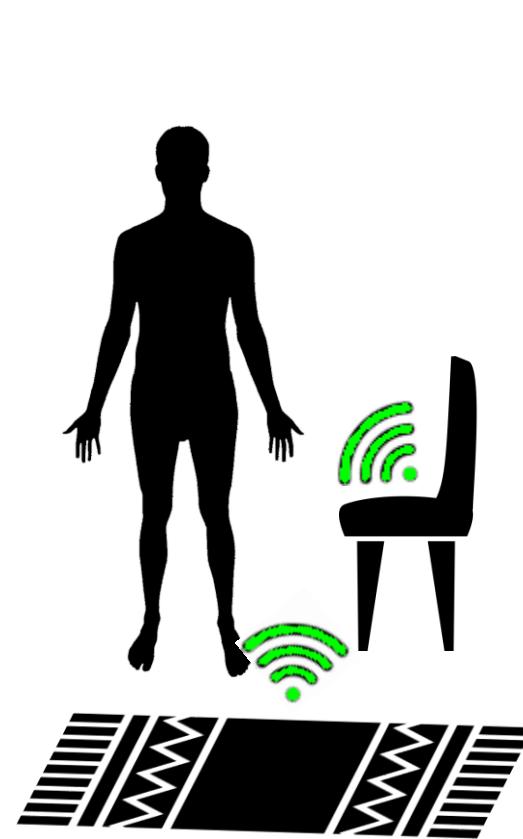


# Fall Detection Systems

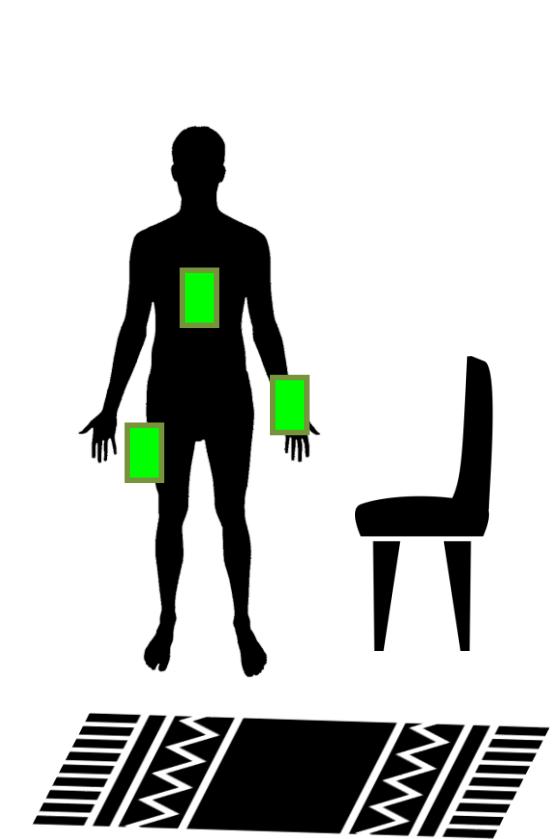
## Vision-based



## Ambient-based



## Wearables

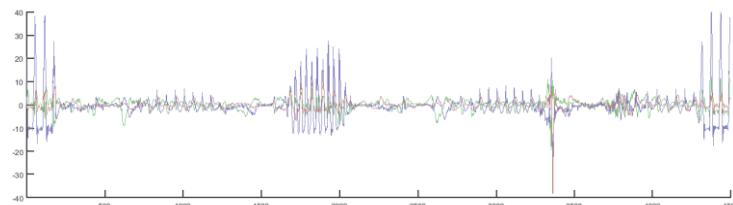


Mubashir, Shao & Seed: A survey on fall detection: Principles and approaches.  
In: Neurocomputing, Volume 100, 2013, Pages 144-152.

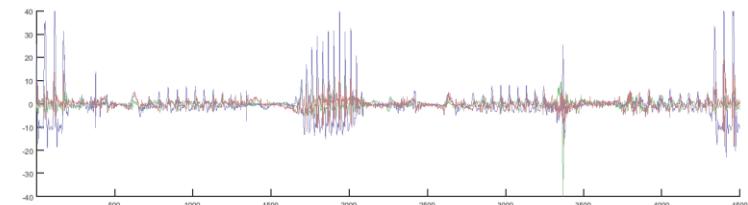
# Positions of Wearables for Fall Detection



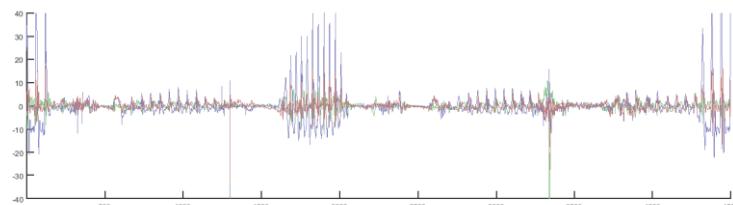
Head



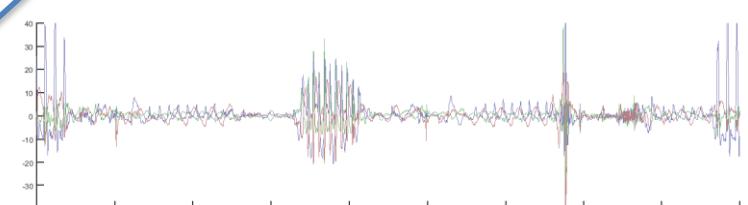
Chest



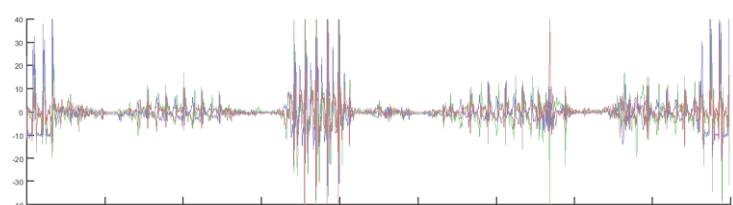
Waist



Wrist



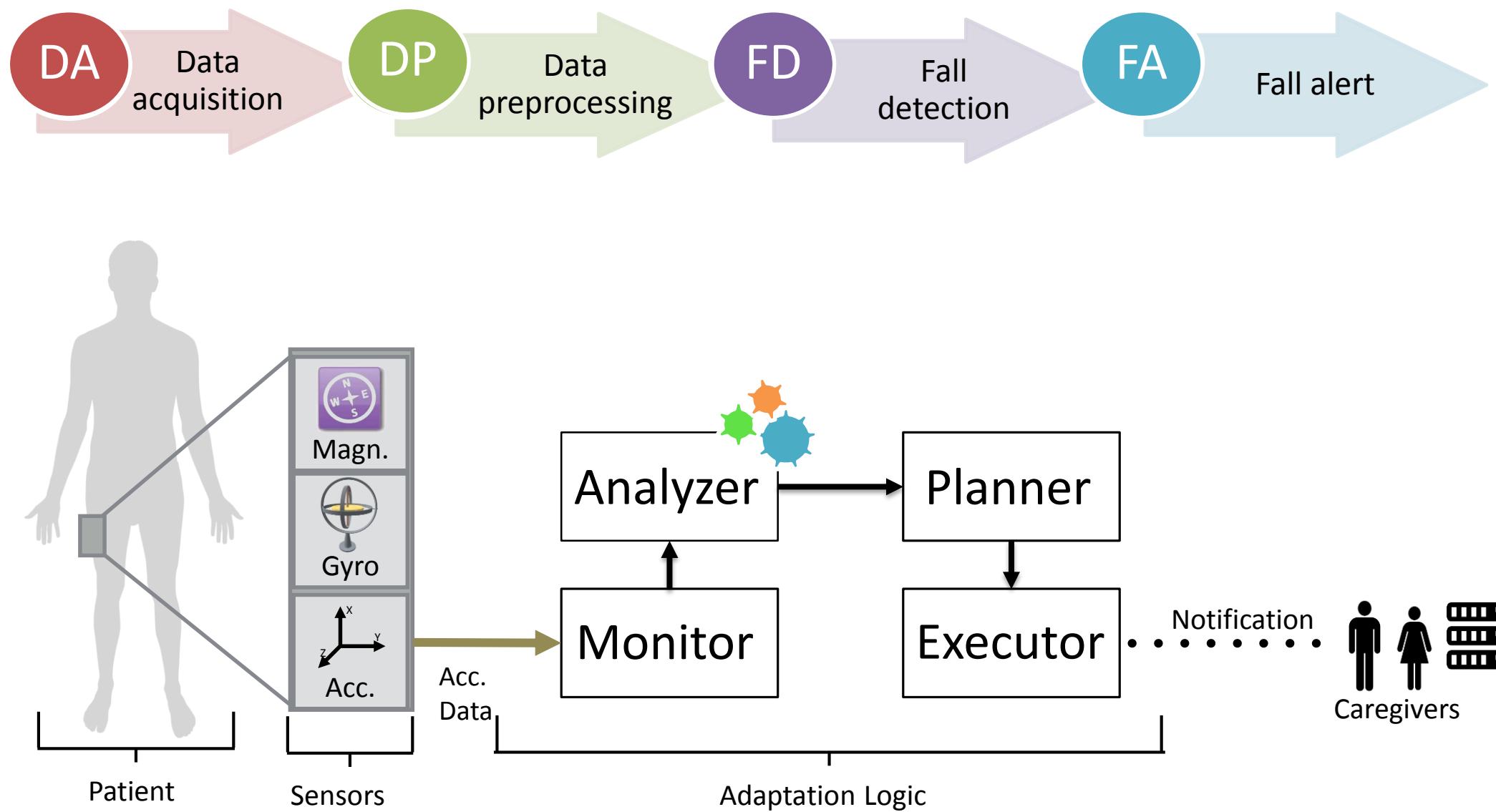
Hip



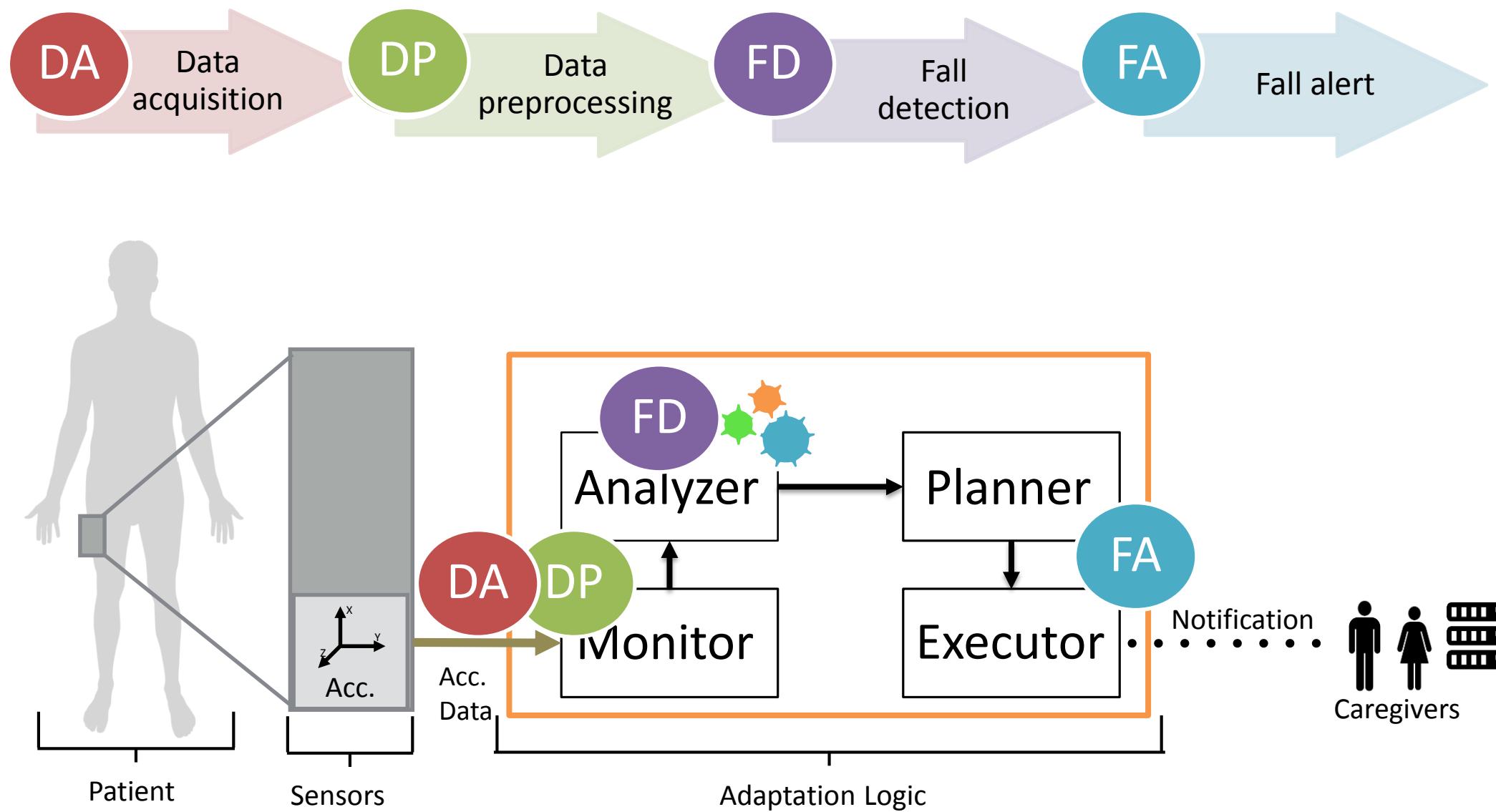
Ankle



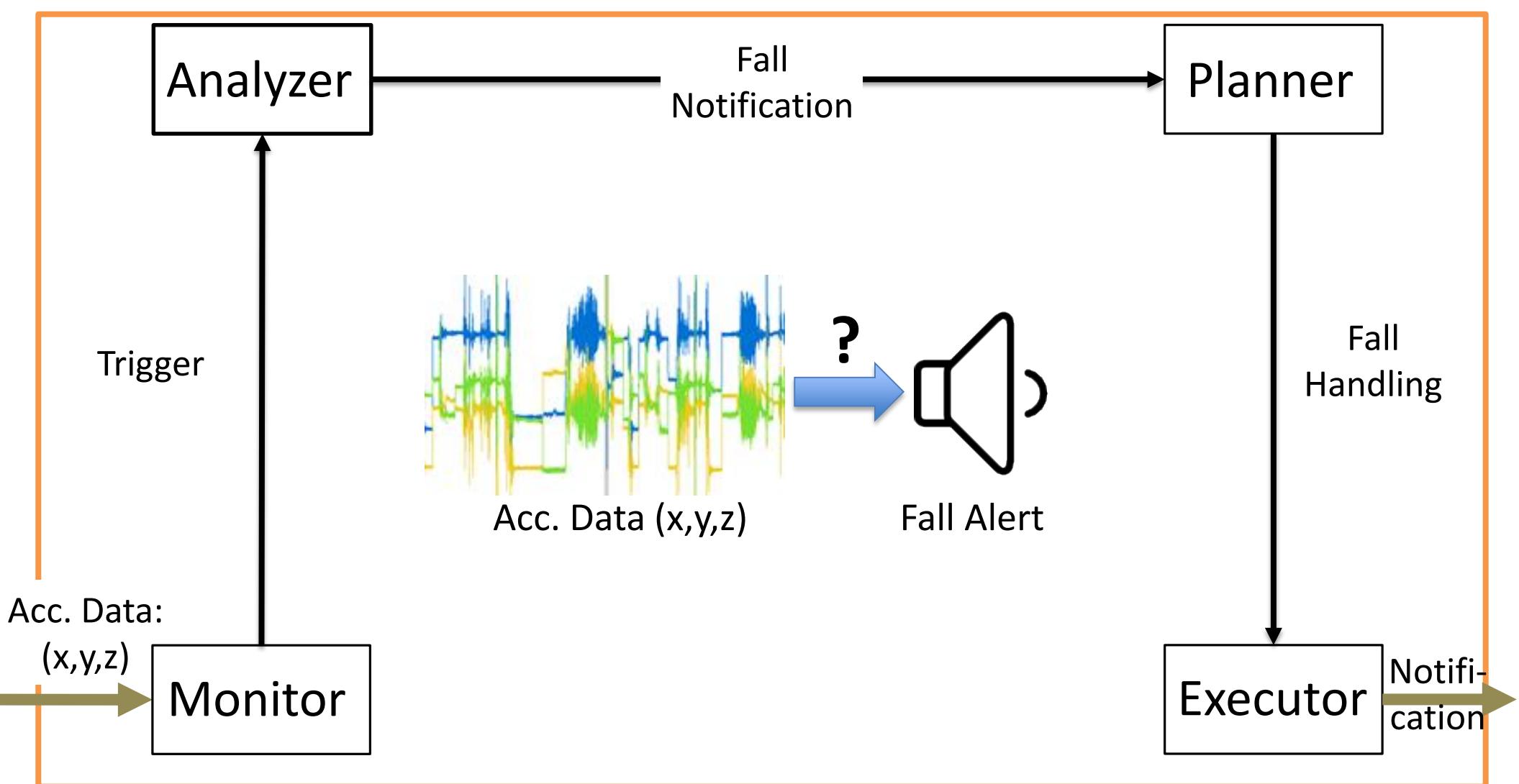
# Self-Adaptive Fall Detection



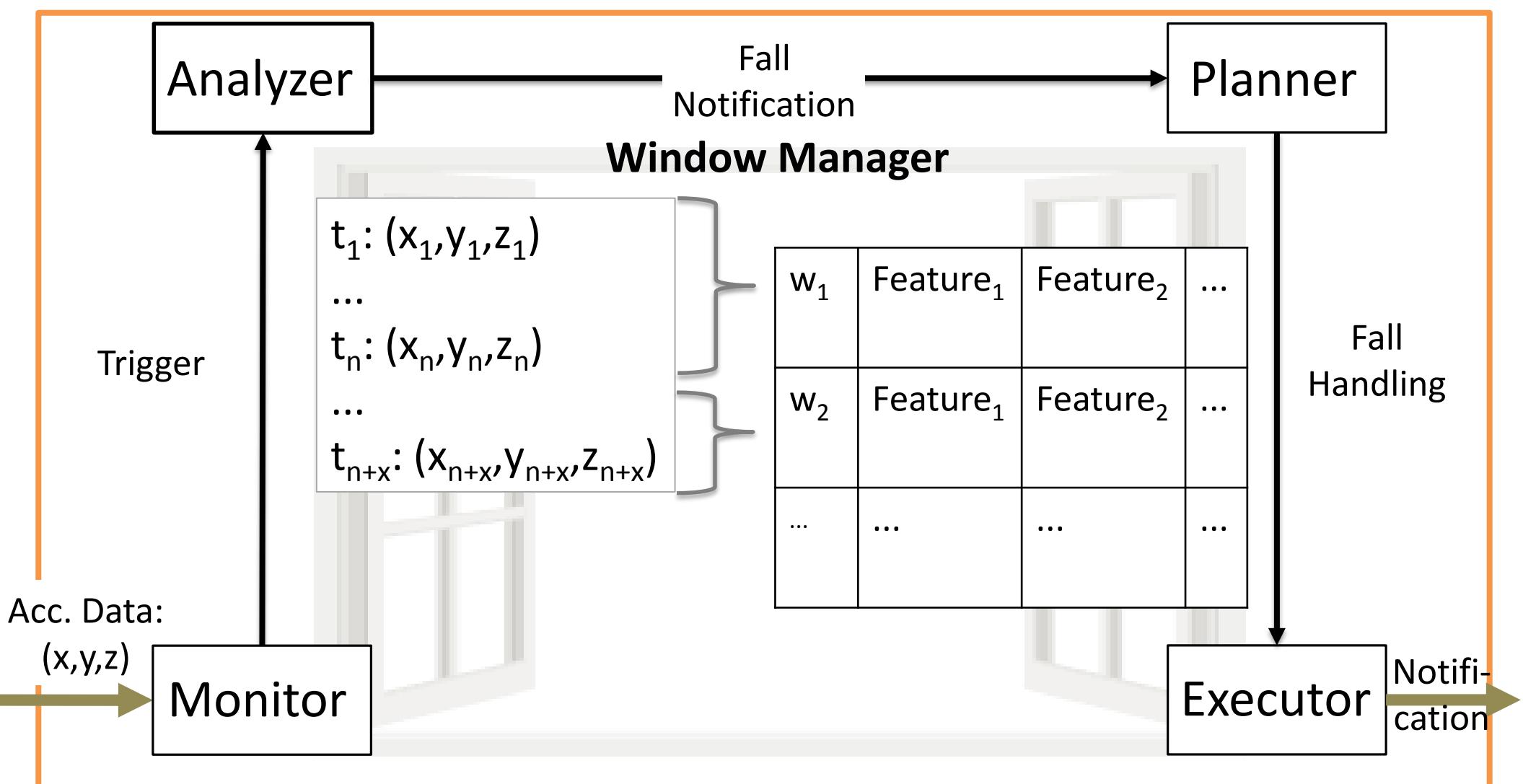
# Self-Adaptive Fall Detection



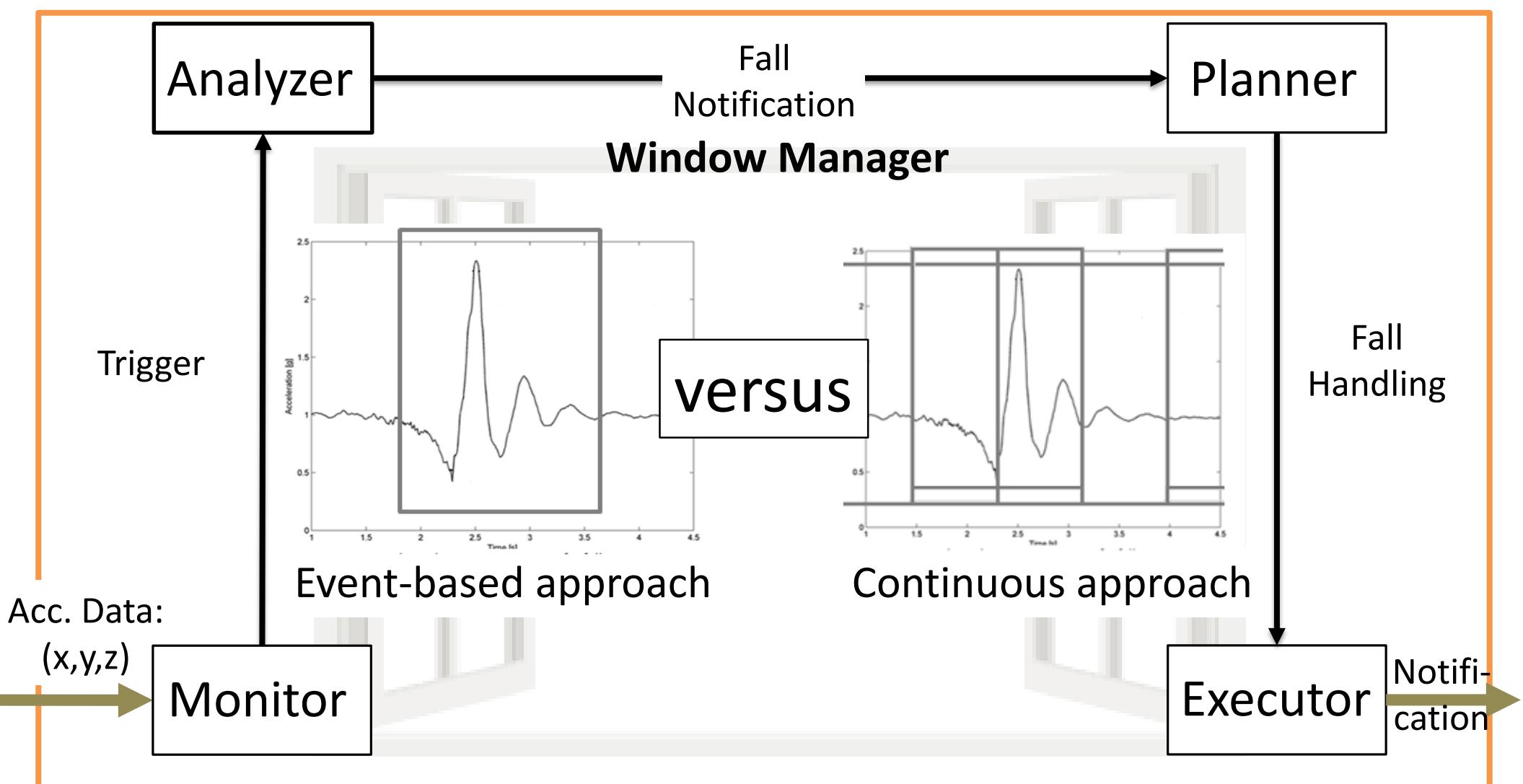
# Implementation: Adaptation Logic



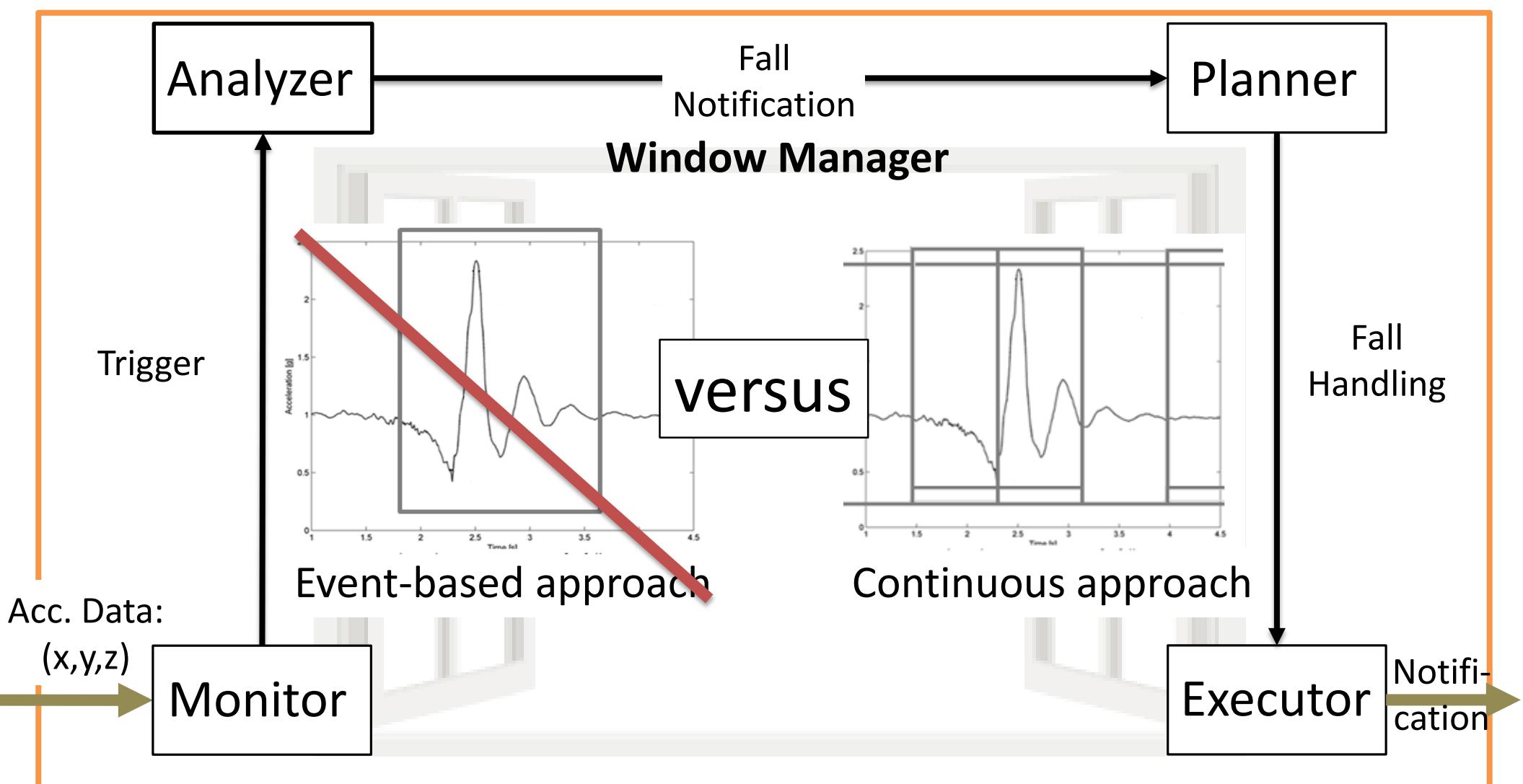
# Implementation: Adaptation Logic



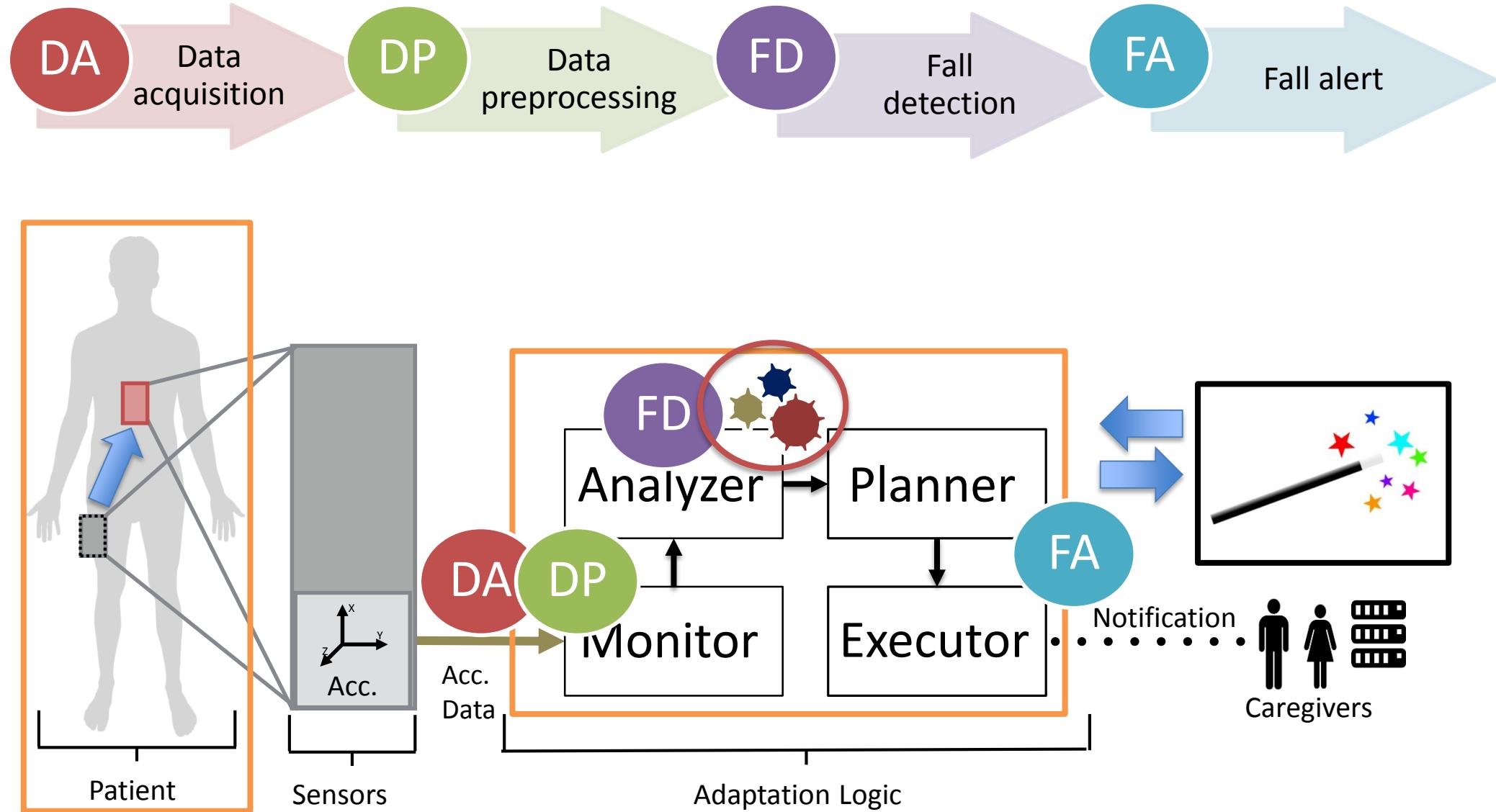
# Implementation: Adaptation Logic



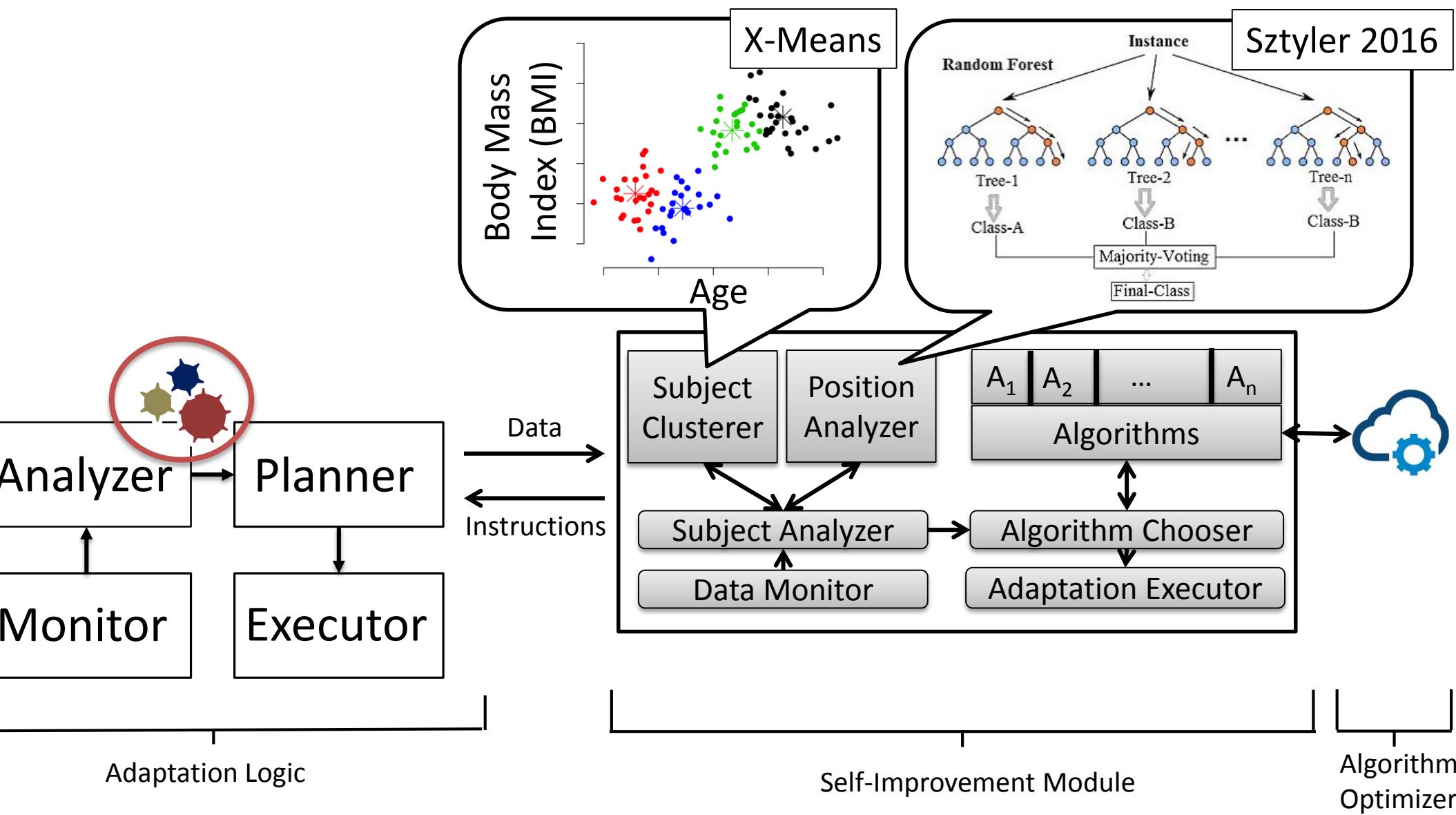
# Implementation: Adaptation Logic



# Self-Adaptive Fall Detection



# Self-Improving Fall Detection



# Evaluation Setting

Propositions:

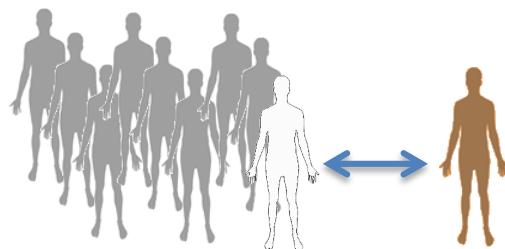
1. Origin of data matters
2. Position matters
3. Self-Improvement matters

Algorithms:

- Classification-based:  
SVM, ANN, Random Forest, k-NN,  
J48 Decision Tree
- Threshold-based (params learned)
- Supports deep learning,  
but dataset is too small

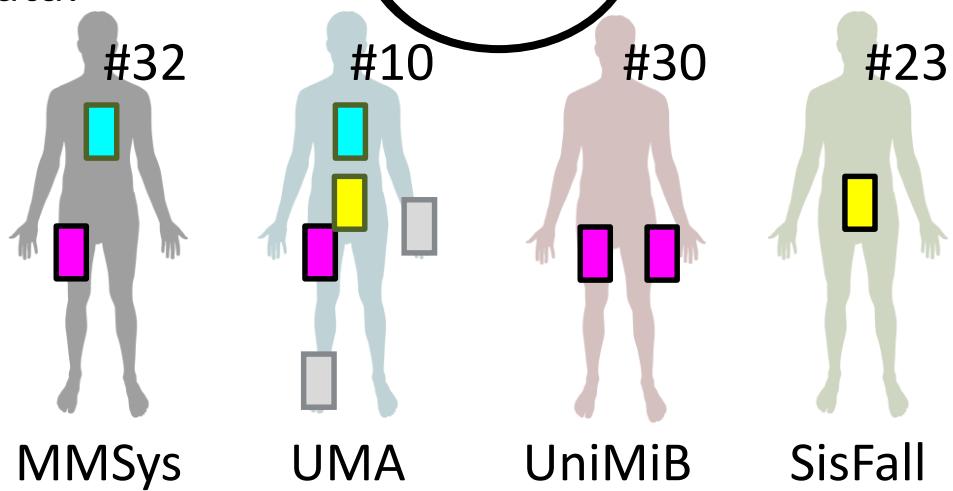


Training of models / evaluation:  
Leave-one-subject-out approach

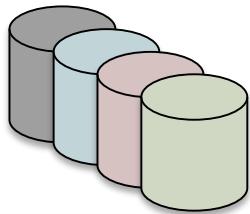


Testing  
Set

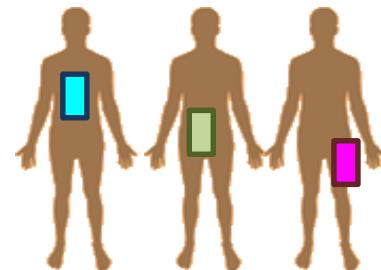
Data:



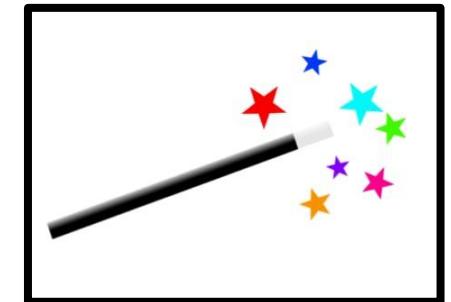
# Evaluation Overview



Experiment 1:  
Cross dataset  
analysis

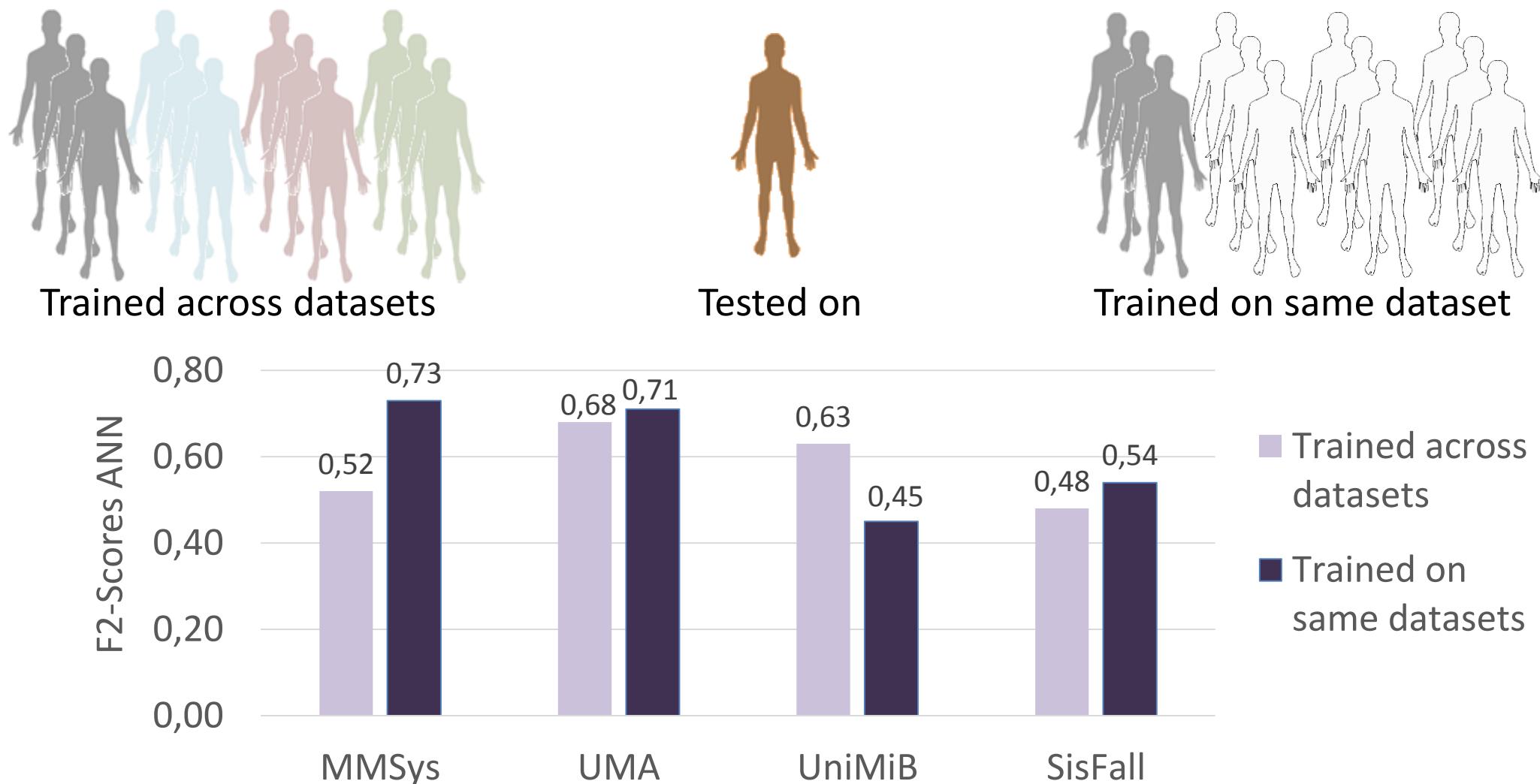


Experiment 2:  
Position-aware  
fall detection



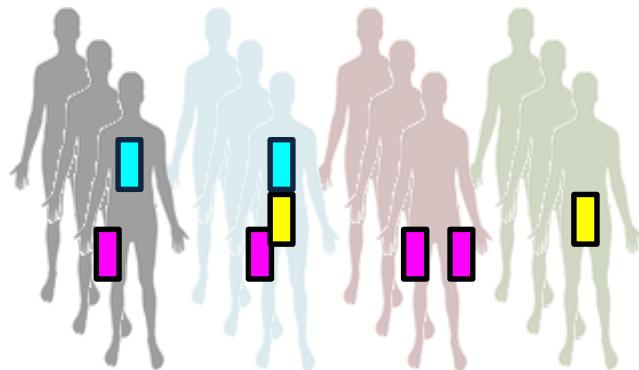
Experiment 3:  
Self-improving  
fall detection

# Experiment 1: Cross-Datasets Fall Detection

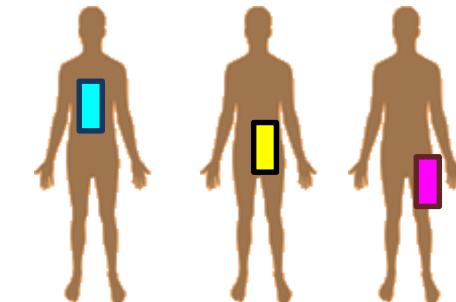


- Proposition 1: Origin of data matters
- The results indicate issues in labeling and setup of capturing data

# Experiment 2: Position-Aware Fall Detection



Trained on one position



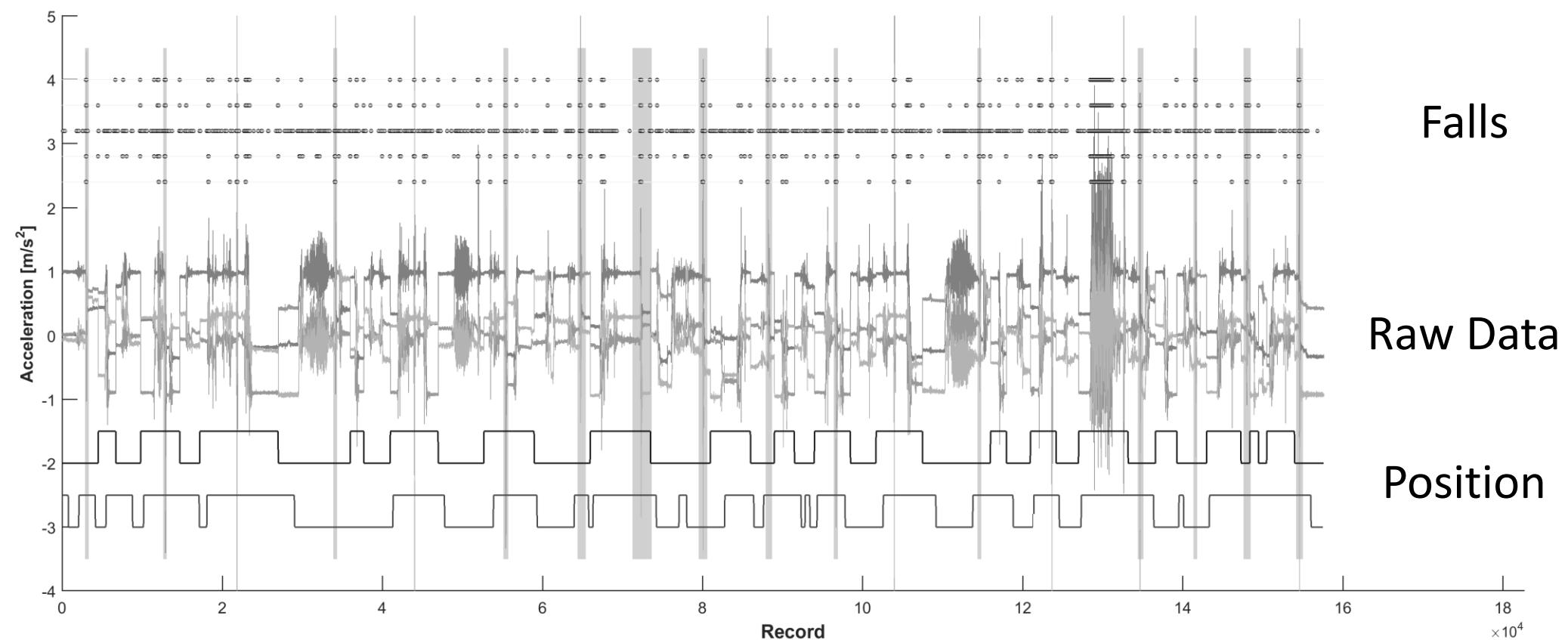
Tested on all positions



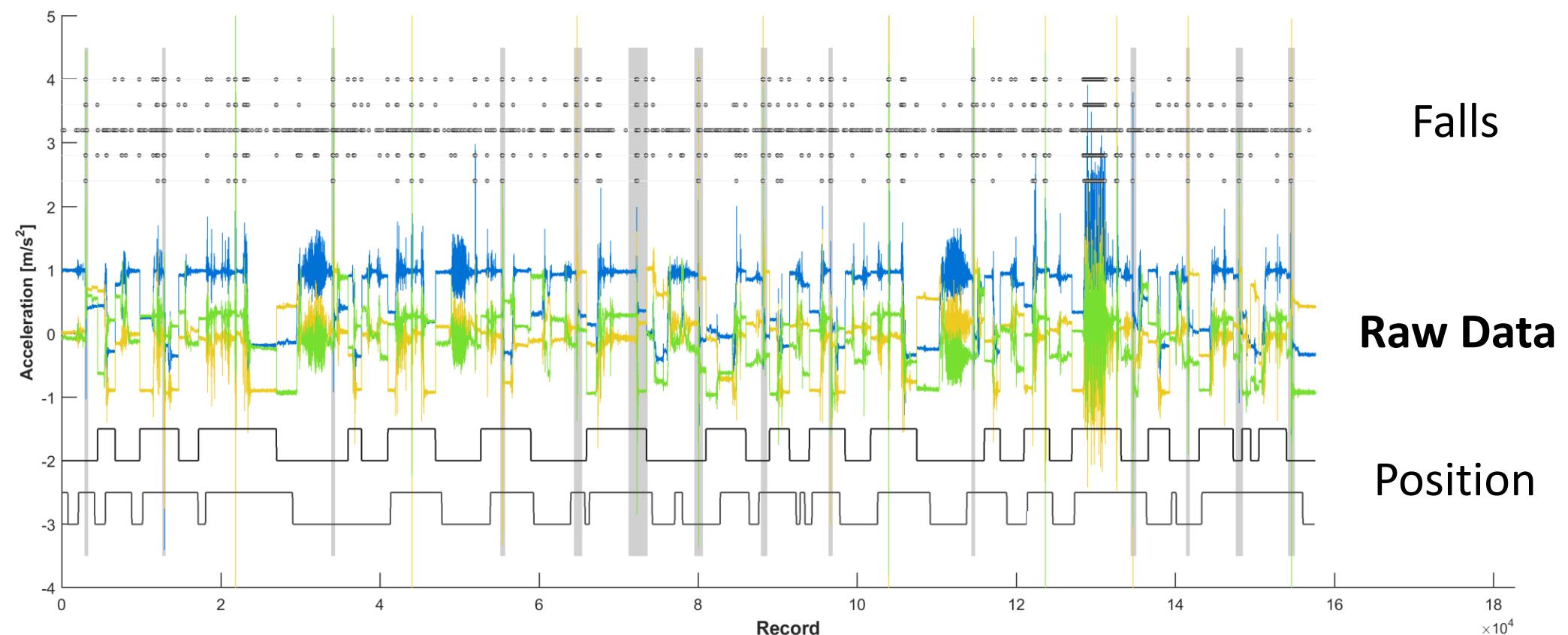
- Proposition 2: Position matters
- The results indicate that hips performed worst



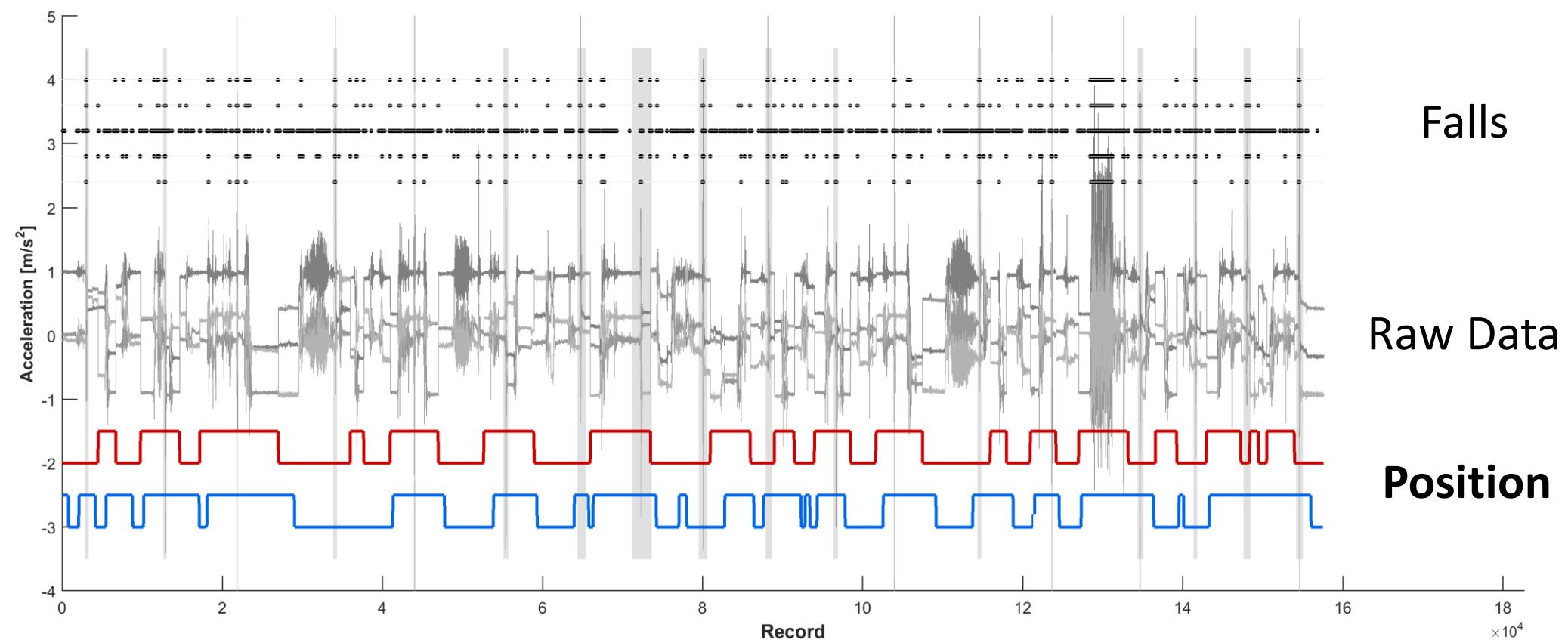
# Experiment 3: Self-Improving Fall Detection



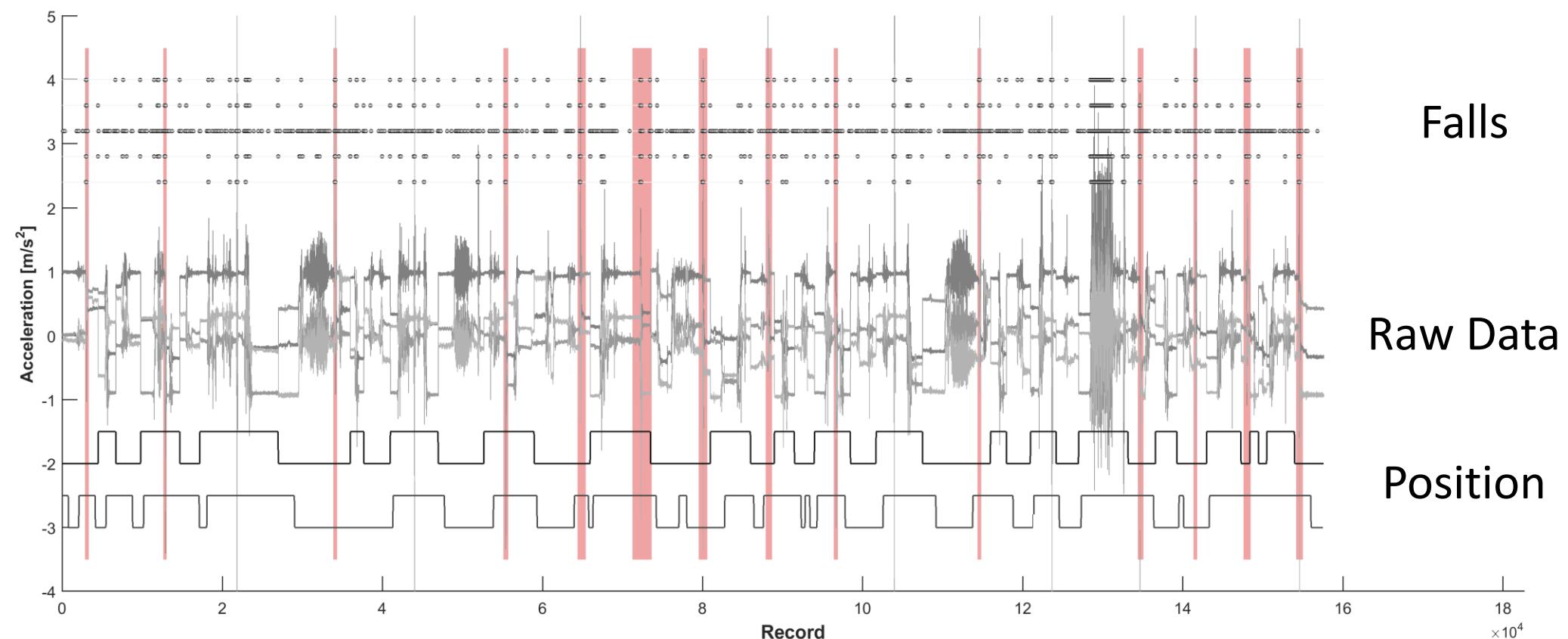
# Experiment 3: Self-Improving Fall Detection



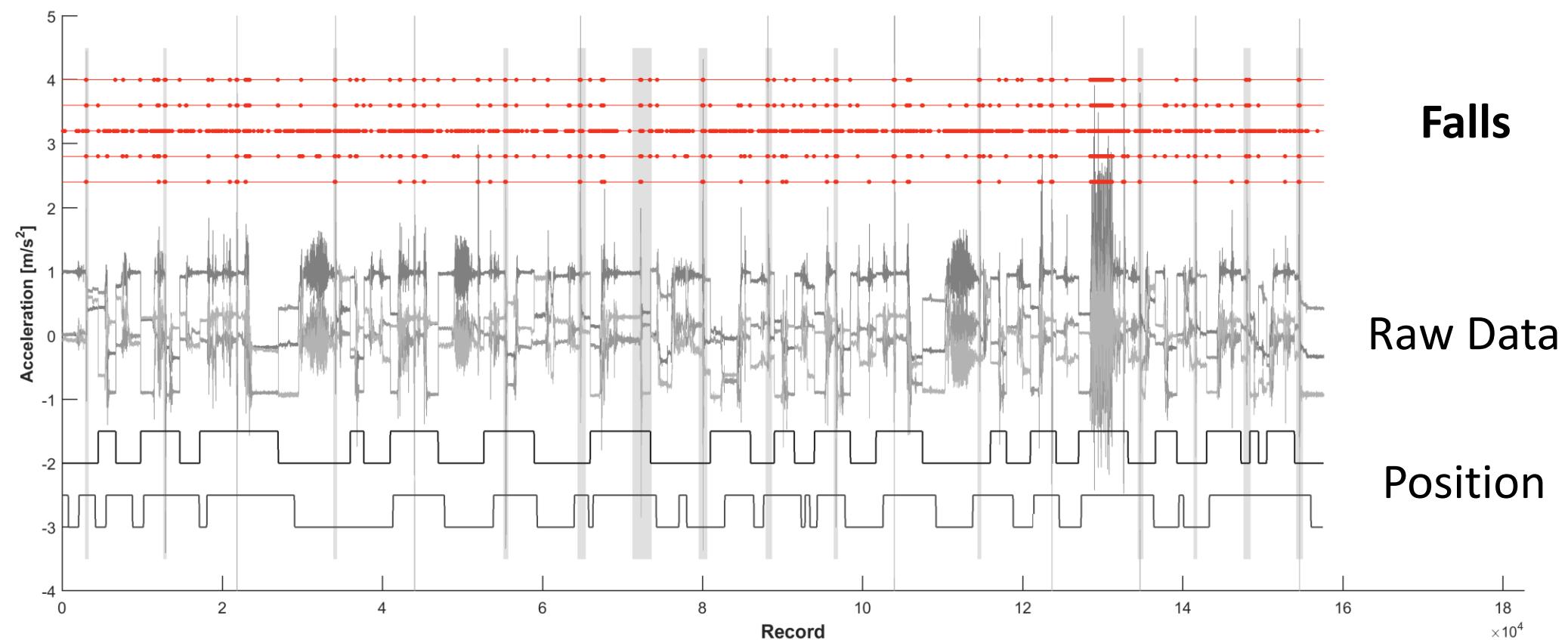
# Experiment 3: Self-Improving Fall Detection



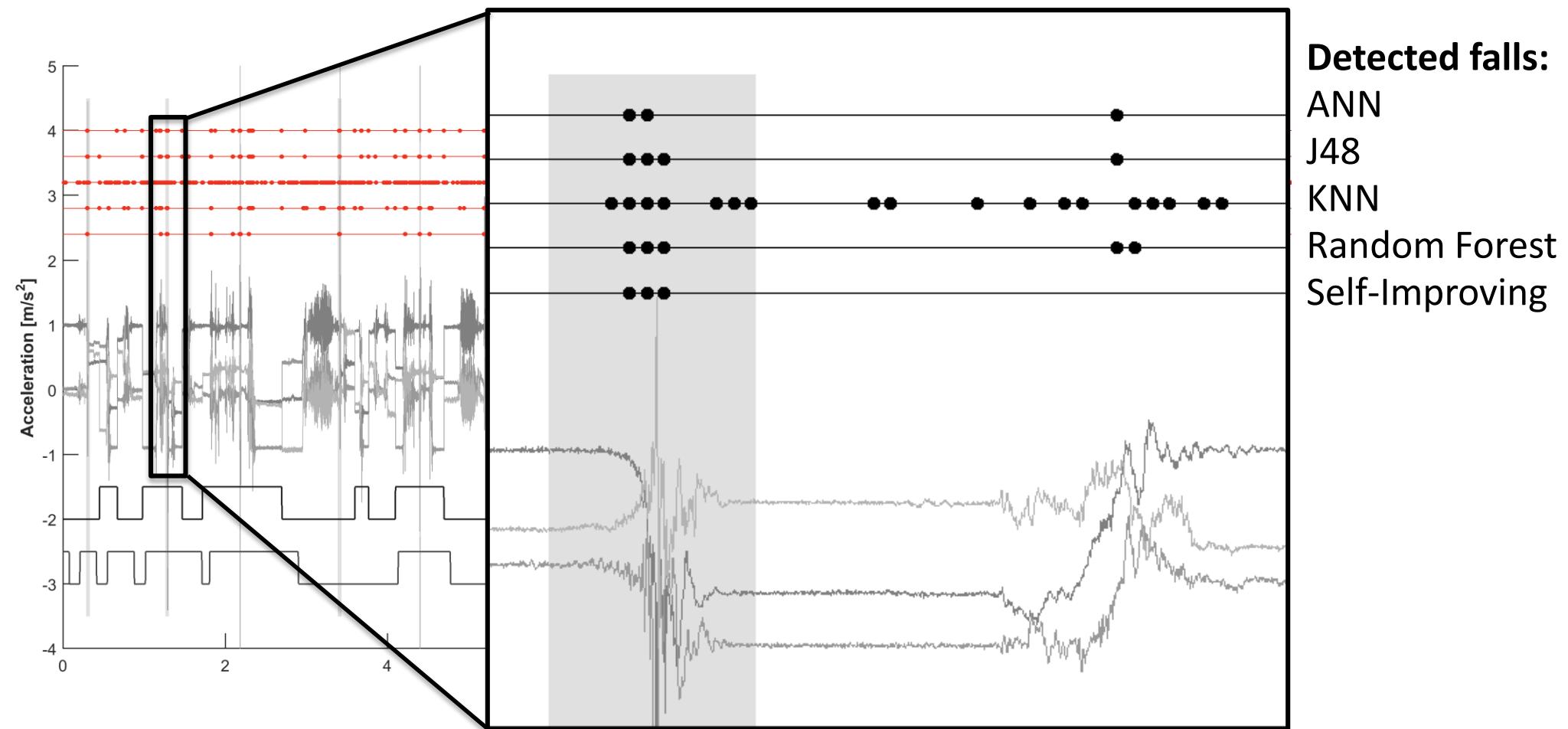
# Experiment 3: Self-Improving Fall Detection



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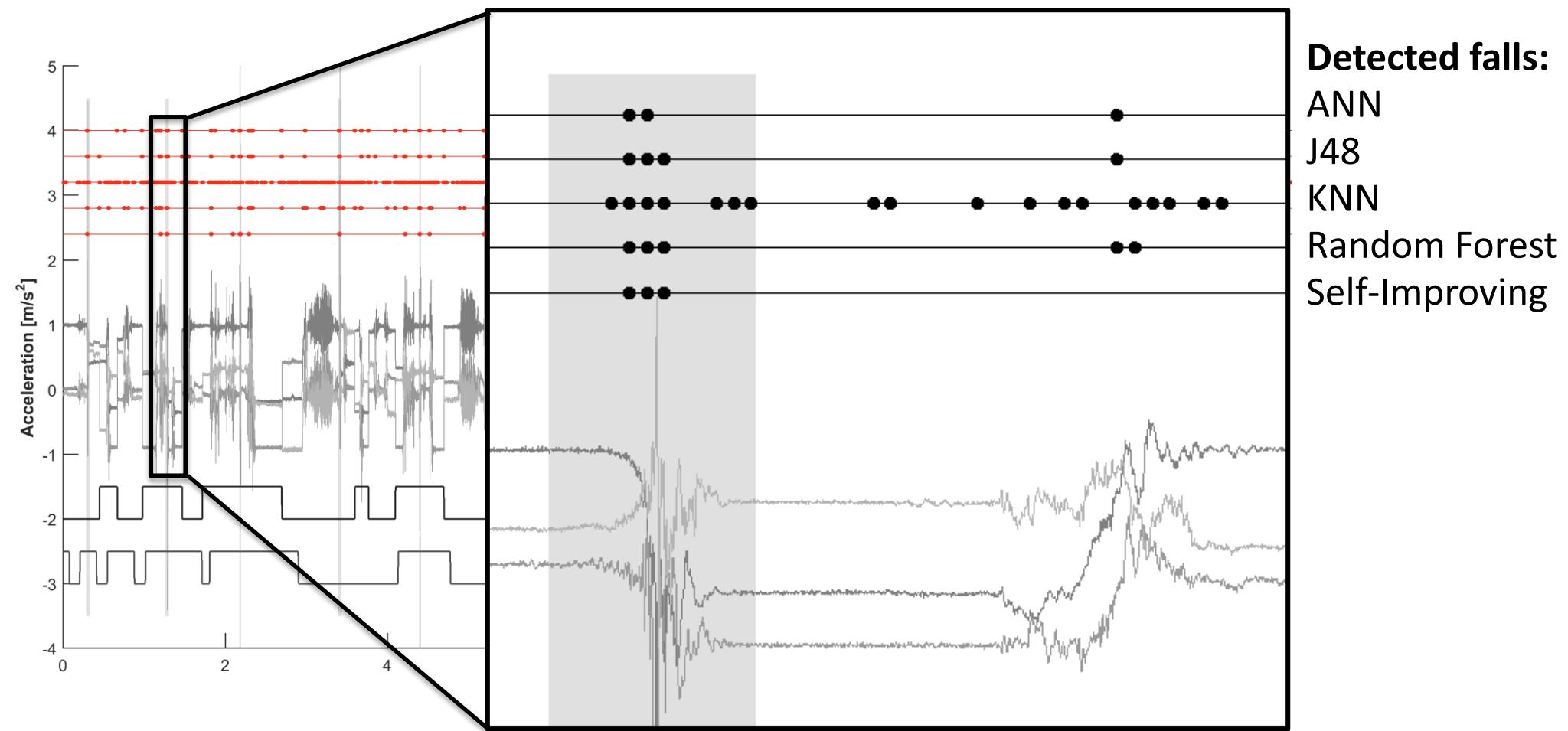


# Experiment 3: Self-Improving Fall Detection



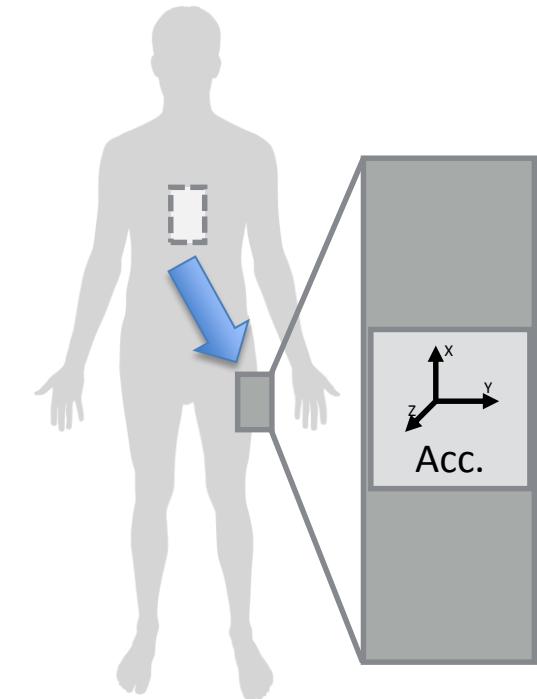
- Recall: 0.93 - Any falls missed?
- No: We missed fall windows, but for each fall we detected at least one window!

# Experiment 3: Self-Improving Fall Detection

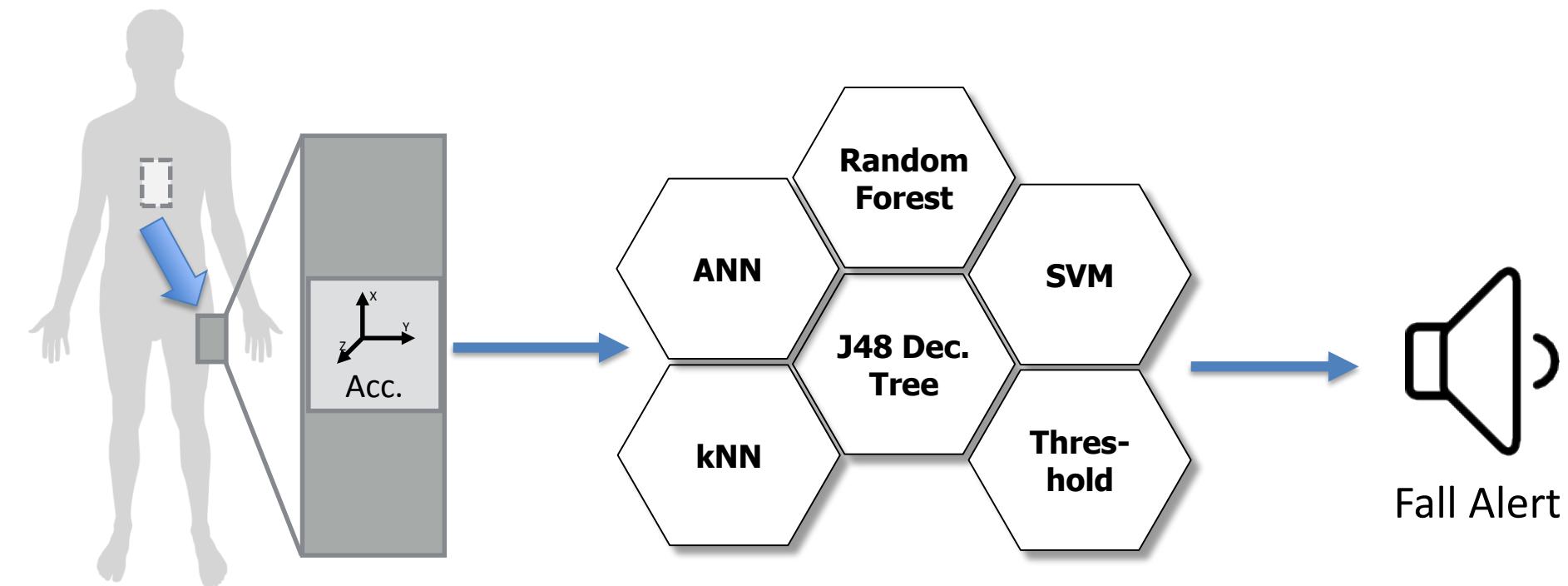


- Proposition 3: Self-improvement matters
- Precision is improved → decreases false positives

# Current State

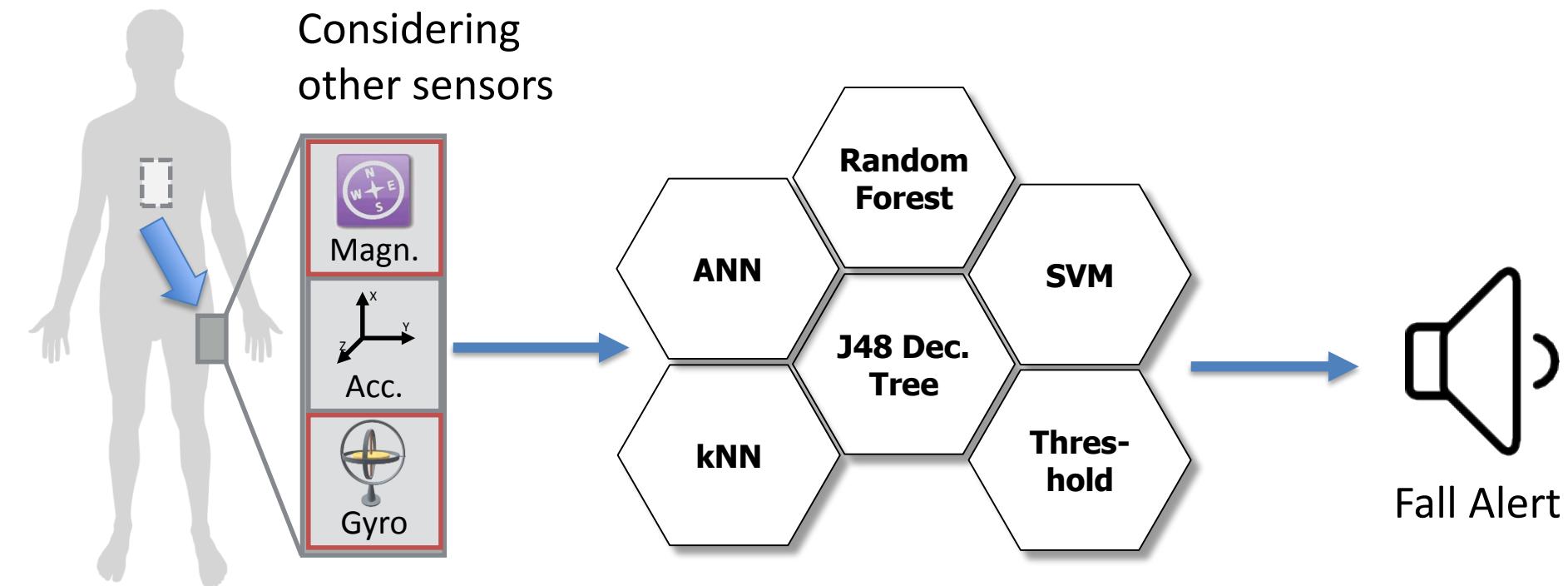


# Current State



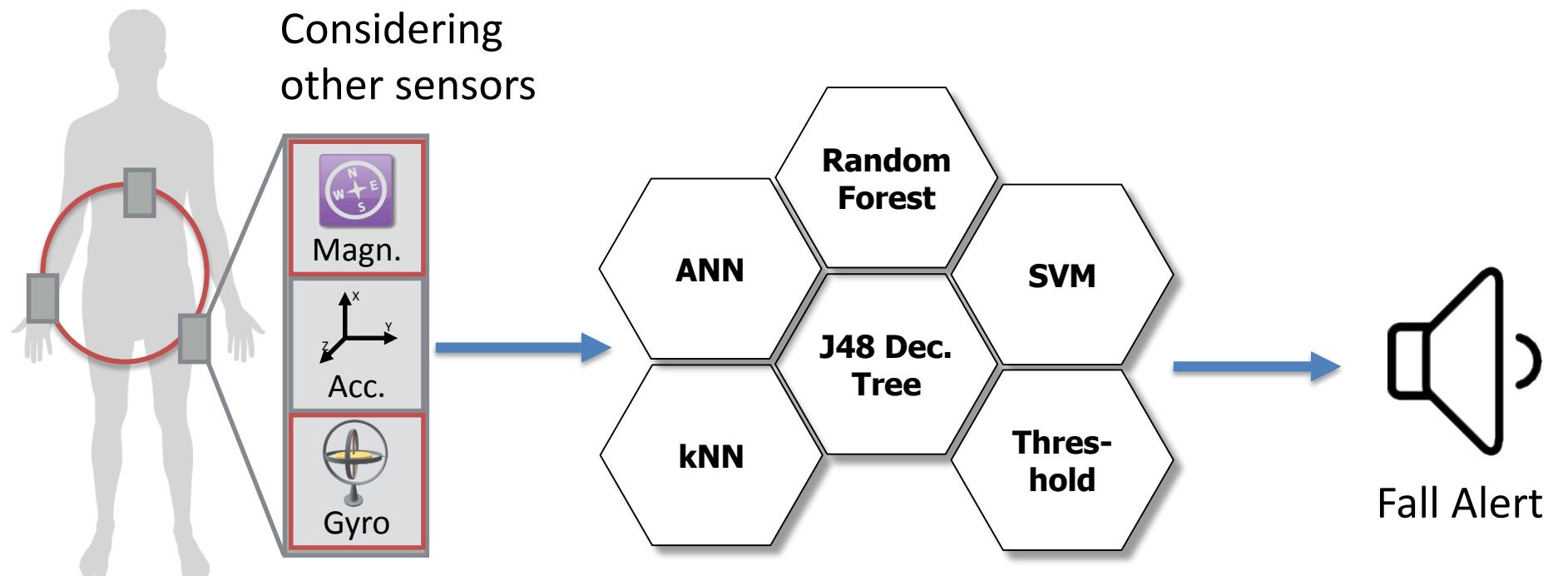
# Future Work

1. Extension:  
Considering  
other sensors



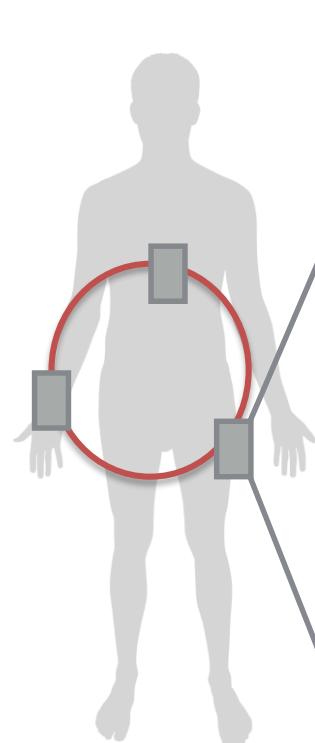
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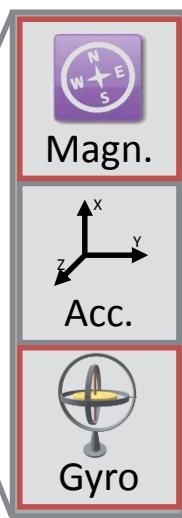


2. Extension:  
Cross-positional  
sensor fusion

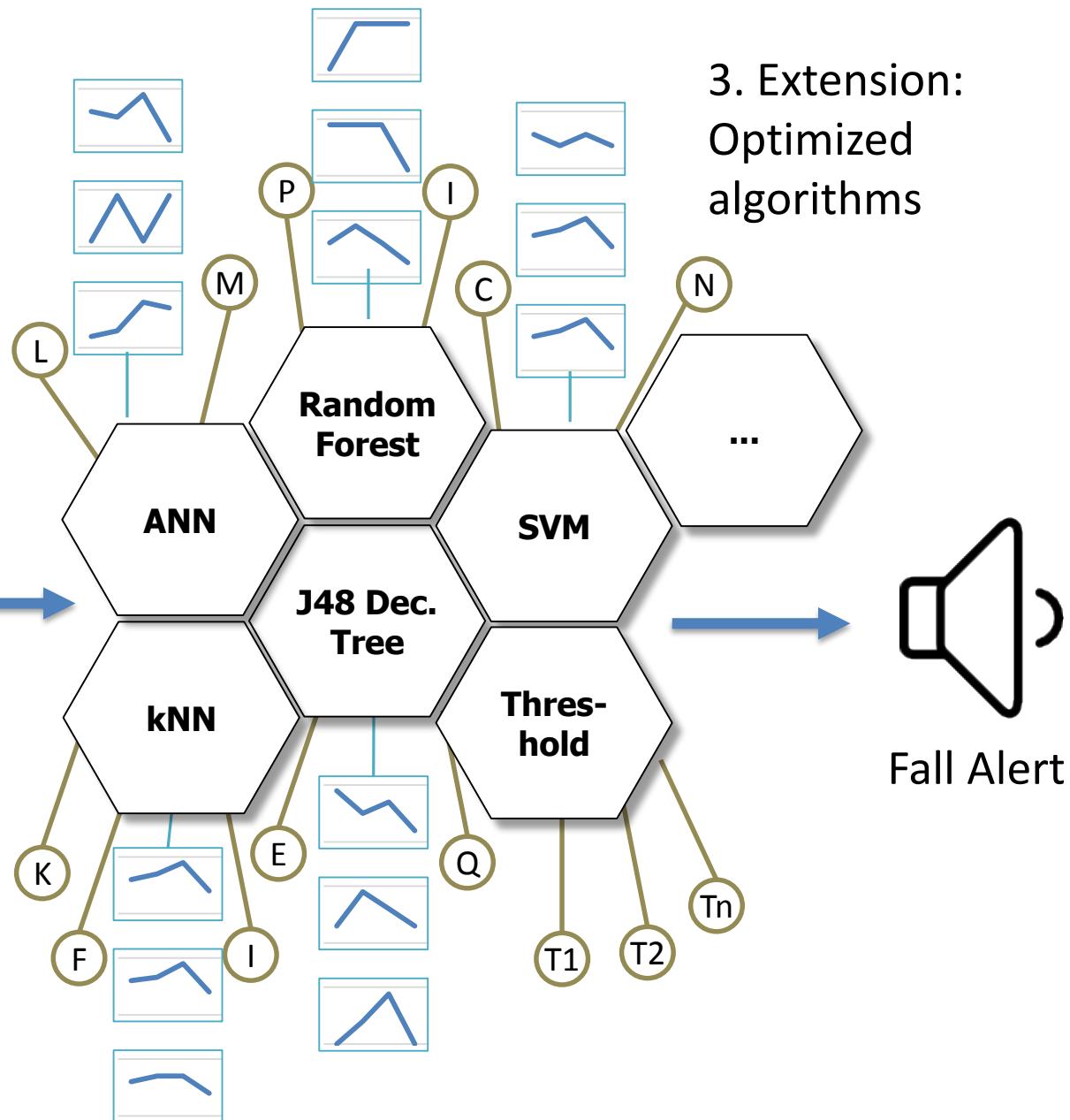
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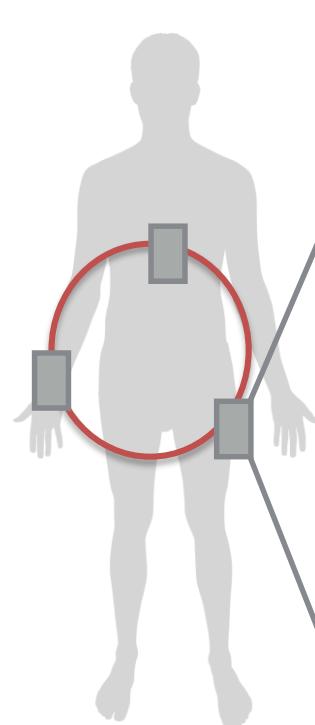


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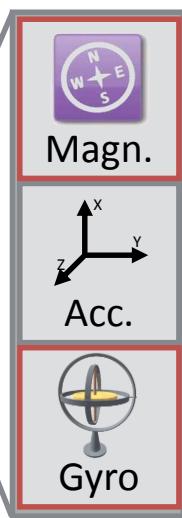


3. Extension:  
Optimized  
algorithms

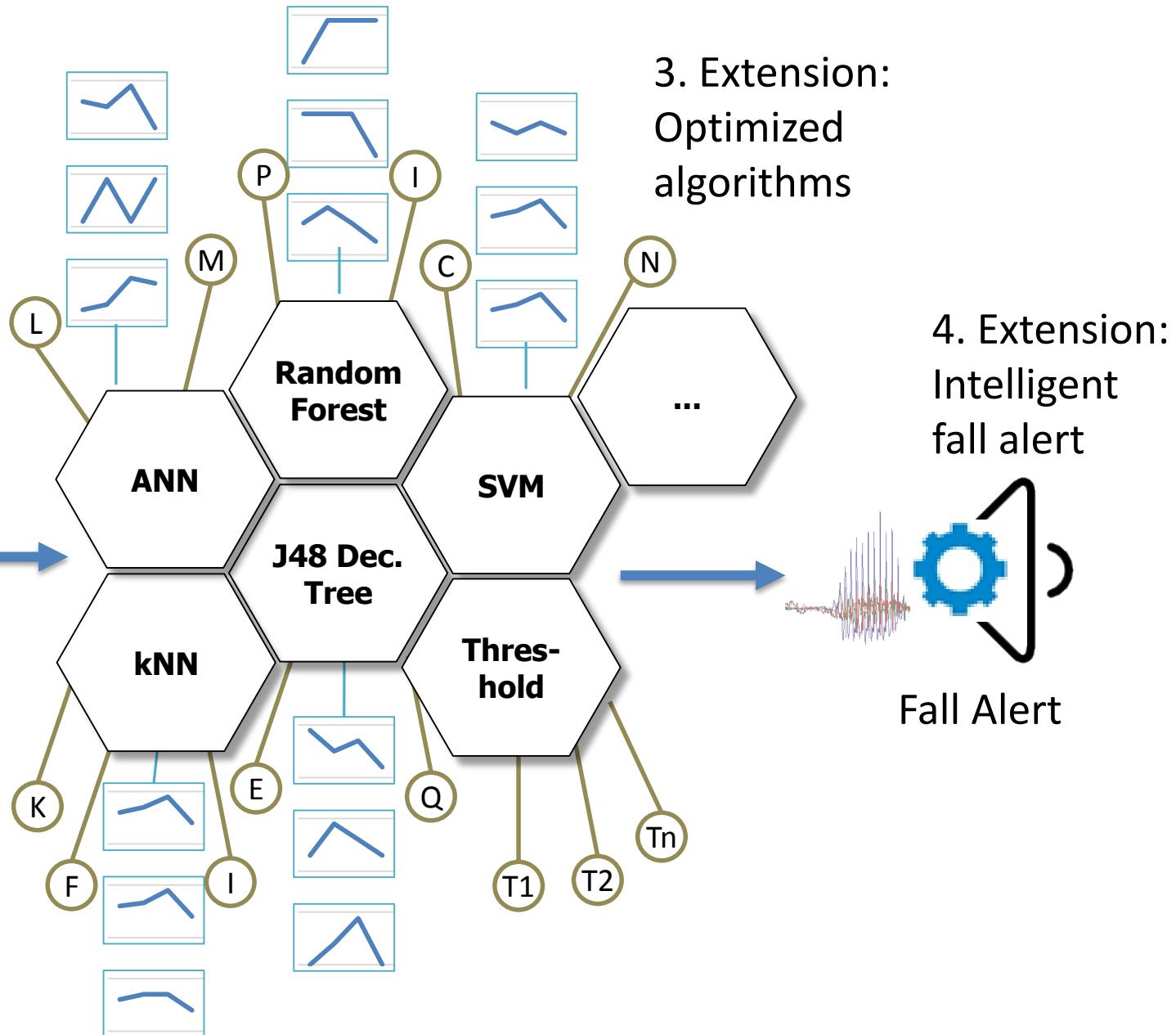
# Future Work



1. Extension:  
Considering  
other sensors



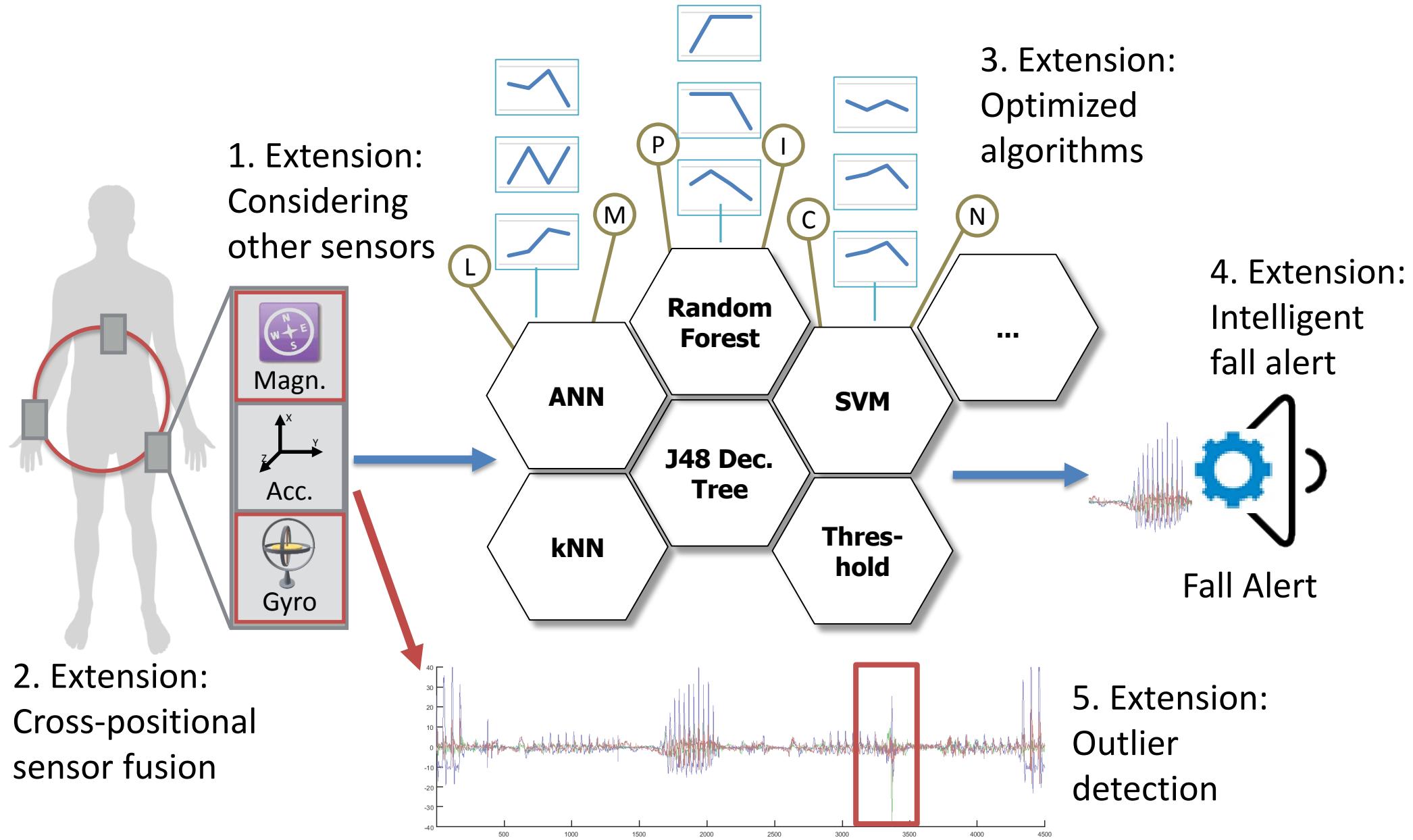
2. Extension:  
Cross-positional  
sensor fusion



3. Extension:  
Optimized  
algorithms

4. Extension:  
Intelligent  
fall alert

# Future Work



# Big Picture

Fall Detection

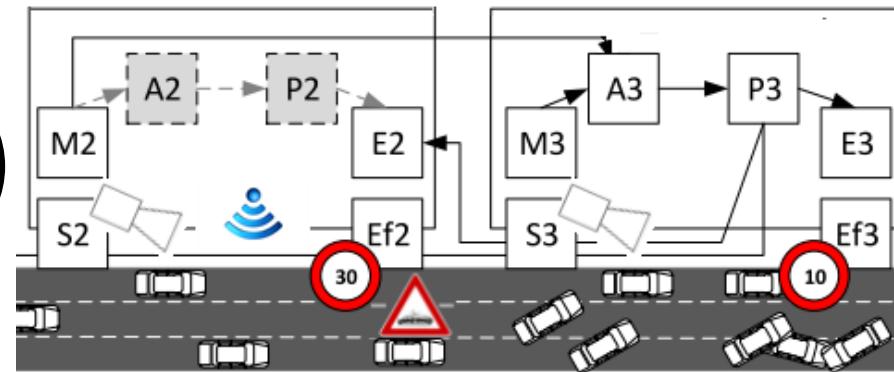


Self-Improvement for  
Pervasive Systems



Smart Vacuum Cleaner [PerIoT17]

Intelligent Transportation Systems [ICAC17]



Your project could appear here...

# The End

